

3/27 Normalizing Flows Cont'd

Invertible maps

$$\begin{array}{ccc} \mathbb{R}^d & & \mathbb{R}^d \\ z & \rightarrow & x \\ \text{latent} & & \text{data} \end{array} \quad \begin{array}{l} x = f_{\theta}^{-1}(z) \\ z = f_{\theta}(x) \end{array}$$

$$z \sim \mathcal{N}(0, 1)^d \quad x \sim p_{\text{data}}(x)$$

$g(z)''$

$$\boxed{p_{\theta}(x) = g(z = f_{\theta}(x)) \left| \frac{\partial f_{\theta}}{\partial x} \right|}$$

can train w/ max likelihood loss

$$L = -\sum_{x \sim p_{\text{data}}} \log p_{\theta}(x)$$

need tractable Jacobian

$$\left| \frac{\partial f_{\theta}}{\partial x} \right| \quad \mathcal{O}(d^3) \text{ operations in general}$$

But if $\odot$ J is upper/lower triangular
only $\mathcal{O}(d)!$

$$\left\{ \begin{array}{l} z_1 = f_1(x_1) \\ z_2 = f_2(x_2; x_1) \\ \vdots \\ z_d = f_d(x_d; x_1, \dots, x_{d-1}) \end{array} \right. \quad \text{Autoregressive transform}$$

$$p(x_1) \rightarrow q(z_1)$$

$$p(x_2 | x_1) \rightarrow q(z_2) \quad \text{each step is transforming 1d conditional dist}$$

$$\vdots$$

$$p(x_d | x_1, \dots, x_{d-1}) \rightarrow q(z_d)$$

$$p(x_1, \dots, x_d) = p(x_1) p(x_2 | x_1) \dots p(x_d | x_1, \dots, x_{d-1})$$

so autoregressive can still model most general joint density!

need family of invertible ~~for~~ 1d fns

— affine $z_n = a_n(x_1, \dots, x_{n-1}) x_n + b_n(x_1, \dots, x_{n-1})$
 can eval all d $\swarrow$ NNS $\swarrow$
 coords w/ single pass - masking

"Masked Autoregressive Flow"

Papamakarios et al 2017

$\left\{ \begin{array}{l} x \rightarrow z \text{ fast (one pass NN) } \mathcal{O}(1) \\ z \rightarrow x \text{ slow (d passes NN) gen.} \end{array} \right.$

IAF defined inverse, $\mathcal{O}(1)$ slow
gen fast

$\left\{ \begin{array}{l} \text{can't train w/ max likelihood} \\ \text{need distillation, teacher/student} \end{array} \right.$

other transforms

- Rational Quadratic Spline

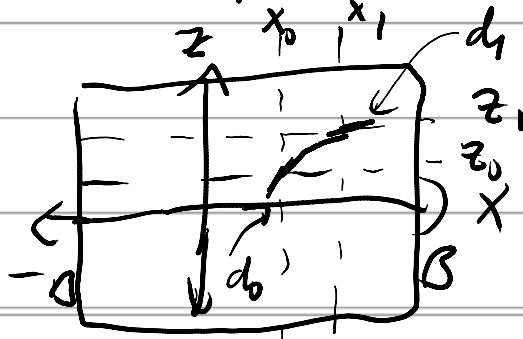
• monotonic
 • has analytic
 inverse

$$z = f(x) = z_0 + (z_1 - z_0) \left(s \xi^2 + d_0 \xi(1-\xi) \right)$$

$$s = \frac{z_1 - z_0}{x_1 - x_0}$$

$$\xi = \left(\frac{x - x_0}{x_1 - x_0} \right) \in (0, 1)$$

$$s + (d_1 + d_0 - 2s) \xi(1-\xi)$$



x_0, x_1
 z_0, z_1
 d_0, d_1

parameters of
spline
NNs

- Coupled layers some simple fn like affine ~ RQS
 (RealNVP (Dinh + 2017)) $z_1 = x_1$ $z_{k+1} = C_{k+1}(x_{k+1}, \mu_{k+1}(x_1, \dots, x_k))$
 $\vdots$ $\vdots$
 $z_k = x_k$ $z_d = C_d(x_d, \mu_d(x_1, \dots, x_k))$
 equally fast DE & gen!
 can be as expressive as MAF w/ perm layers

- Glow based on affine coupled layers
 + multiscale
 → towards data science
 explainer
 + MNIST example

Calo Flow (2106.05285)
 example